



CPSC 424

Curves:

Implicit vs. Explicit vs. Parametric

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Syllabus

Curves in 2D and 3D

- **Implicit vs. Explicit vs. Parametric curves**
- Basis functions and Splines
- Hermite and Bezier curves
- Elementary differential geometry
- Other bases
- Subdivision Curves
- 2D Implicits: Analytical and Neural

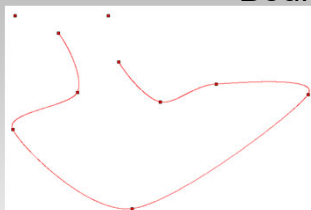
Surfaces

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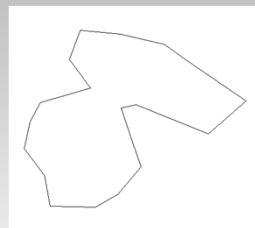
How to represent shape (2D or 3D)?

Geometry – Curves/2D shapes

- Boundary representations



**Freeform
(aka smooth)**



**Discrete:
polylines**

- Alternatives:



Primitive based



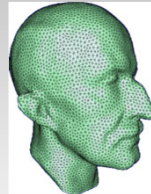
Pixel based

How to represent 3D shape?

- Most common: Boundary representations

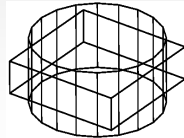


**Freeform
– smooth
surface**

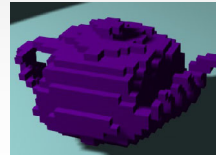
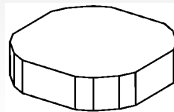


**Mesh –
polygonal
surface**

- Alternative: Volumetric representations



Primitive based



Voxel based

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Modeling Geometry

Approaches:

- Fixed set of primitives
 - Curves: *lines, circles, rectangles...*
 - Surfaces: *spheres, cylinders...*
 - *Hard to assemble arbitrary (smooth) geometry*
- Freeform curves/surfaces
 - *Single representation for arbitrarily complex geometry*
 - *Curves and surfaces as functions with built-in smoothness properties*
 - *Bézier curves, splines*
- Discrete: meshes, points, splats

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Curves: Explicit vs. Implicit vs. Parametric

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Curves & Surfaces as Explicit Functions

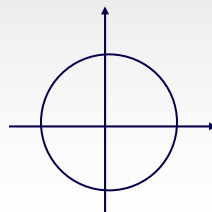
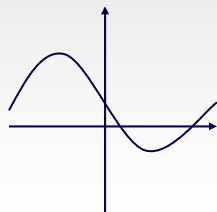
Curves:

$$y = F(x)$$

Surfaces:

$$z = F(x, y)$$

Examples:



Not a function in Cartesian coord.,

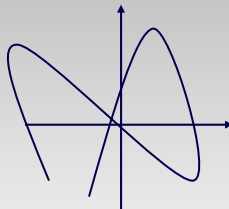
$$y = \pm\sqrt{1-x^2}$$

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Curves & Surfaces as Explicit Functions



Not representable as a function:



Limitations of explicit functions:

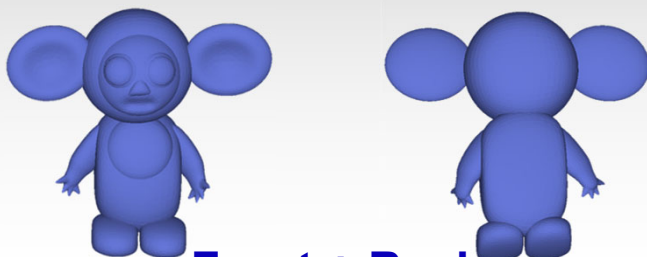
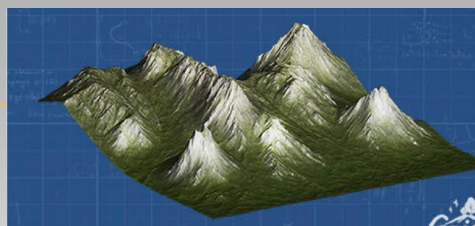
- Cannot model every curve in 2D
- No true 3D curves possible
 - All curves confined to a plane

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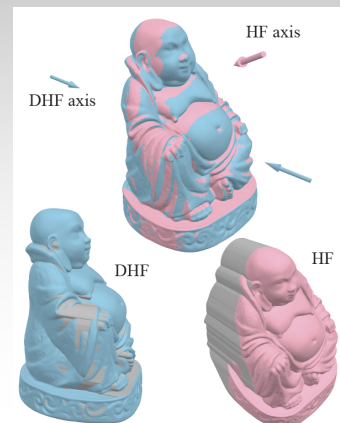
Explicit Functions

Uses

- Graphs (one Y per X, one Z per (X,Y))
- Terrain modeling (no caves)
- Complex shapes as Boolean combinations (intersections) of explicits



Front + Back



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Curves & Surfaces as Implicit Functions



Curves

$$F(x, y) = 0$$

Surfaces

$$F(x, y, z) = 0$$

Interpretation for curves:

- Iso-lines (contours) in a terrain

Property:

- If F is continuous, implicit curves and surfaces are always closed or extend to infinity

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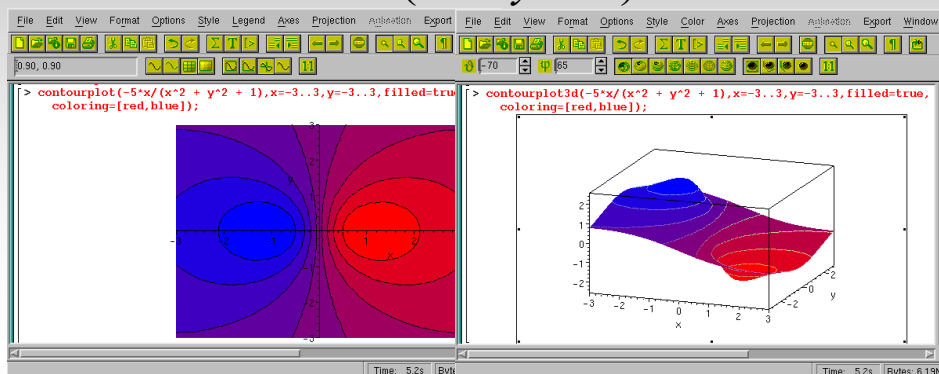
Curves & Surfaces as Implicit Functions



Examples:

$$x^2 + y^2 - 1 = 0$$

$$-5x/(x^2 + y^2 + 1) = c$$



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Curves & Surfaces as Implicit Functions

Conversion:

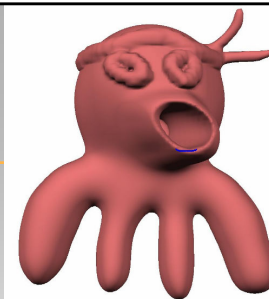
- Explicit to implicit: trivial
- Implicit to explicit: hard
 - Solving for y involves root finding!

$$y - F(x) = 0$$

Useful for many settings including modeling & machine learning

Limitations:

- Curves only in 2D
 - Non degenerate implicits in 3D are surfaces
- Often unintuitive
- Relatively costly to render (typically use ray tracing)



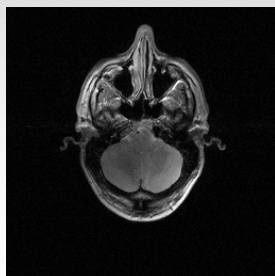
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Implicit Functions in Medical Imaging

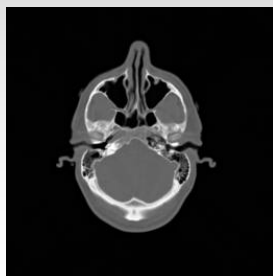


Data:

- CT & MRI scanners produce volume of *density* values $F(x,y,z)$
- Individual features (bone surface, brain surface) are iso-surfaces of the volume: $F(x,y,z)=c$



MRI

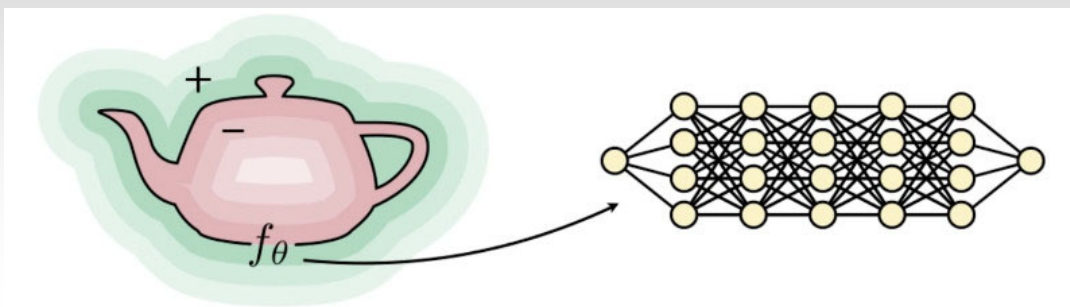


CT

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Implicit Functions in ML

- Allow for regular grid representation
 - *Simplifies encoding*
- Or direct functional encoding
 - *Learning values at locations in space*



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Curves & Surfaces as Parametric Functions

Concept:

- Curve as function of artificial “time” parameter t

2D curve:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} F_x(t) \\ F_y(t) \end{pmatrix} =: F(t); F : \mathcal{R} \mapsto \mathcal{R}^2$$

3D curve:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} F_x(t) \\ F_y(t) \\ F_z(t) \end{pmatrix} =: F(t); F : \mathcal{R} \mapsto \mathcal{R}^3$$

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Curves & Surfaces as Parametric Functions



Curve example:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \cos t \\ \sin t \\ t \end{pmatrix}$$

Surfaces (in 3D):

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} F_x(s, t) \\ F_y(s, t) \\ F_z(s, t) \end{pmatrix} = F(s, t); F : \mathcal{R}^2 \mapsto \mathcal{R}^3$$

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Curves & Surfaces as Parametric Functions



This works in arbitrary dimensions!

- Curves:

$$\mathbf{x} = F(t); F : \mathcal{R} \mapsto \mathcal{R}^d$$

- Surfaces:

$$\mathbf{x} = F(s, t); F : \mathcal{R}^2 \mapsto \mathcal{R}^d$$

- Hypersurfaces:

$$\mathbf{x} = F(\mathbf{t}); F : \mathcal{R}^n \mapsto \mathcal{R}^d; n < d$$

Notation:

- Bold variables ($\mathbf{t}, \mathbf{x}$) denote vectors, while italics denote scalars (t, d).

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Parametric Curves

Advantage:

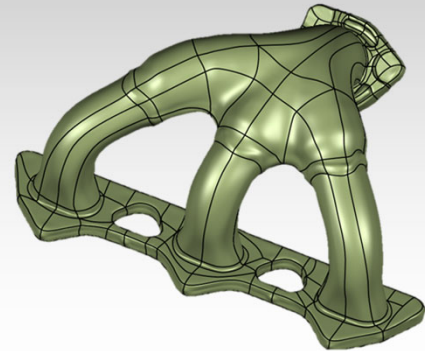
- Arbitrary curves in arbitrary dimensions

Parametric functions:

- High degree of control
 - “easy” to create from scratch
- Efficient Rendering
- Storing Signals
 - Use same parametric representation

Use case

- Most 3D assets
 - Engineering, games, movies...



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Parametric Curves

Challenges:

- Control?
 - Try to find a formula for a specific curve you have in mind?
- Encoding?
 - Arbitrary mathematical functions?

Solution:

- Restrict yourself to specific class of functions

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Surfaces

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Spline Curves

Description = basis functions + coefficients

$$F(t) = \sum_{i=0}^n P_i B_i(t) = (x(t), y(t))$$

$$x(t) = \sum_{i=0}^n P_i^x B_i(t)$$

$$y(t) = \sum_{i=0}^n P_i^y B_i(t)$$

- Same basis functions for all coordinates

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Example: Polynomial Curves

Polynomial Curves:

- Restrict to polynomial functions of degree $\leq m$:

$$\mathbf{x} = \sum_{i=0}^m \mathbf{b}_i t^i$$

- Note: $\mathbf{b}_i$ are vectors!
- Example curve in 2D:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \sum_{i=0}^m \begin{pmatrix} b_{x,i} \\ b_{y,i} \end{pmatrix} t^i$$

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Polynomial Curves

Advantages:

- Computationally easy to handle
 - $\mathbf{P}_0 \dots \mathbf{P}_n$ uniquely describe curve (finite storage, easy to represent)

Disadvantages:

- Not all shapes representable
- Not intuitive – how to relate coefficients to intended shape

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Polynomial Curves

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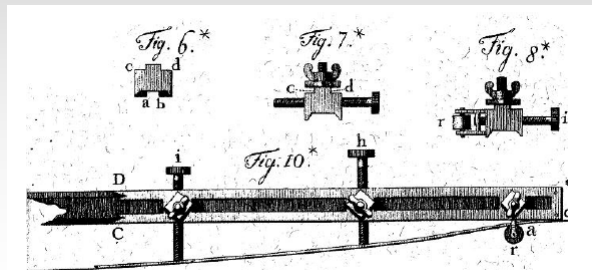
- Not all shapes representable
- Not intuitive – how to relate coefficients to intended shape

What basis functions B_i should we use?

Splines: parametric curves over geometric basis

Geometric meaning of coefficients

- Approximate/interpolate set of positions, derivatives, etc..





Example: Curves in PowerPoint

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Parametric Spline Curves

Commonly used classes:

- Polynomials
 - ***Bézier, Hermite***
- Piecewise polynomials
 - *B-splines*
- Rational and piecewise-rational curves
 - *Rational Bézier curves, rational B-splines (NURBS)*
- Neural (not strictly splines)

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